Oriental motor

Rack and Pinion System
L Series *Q_STEP* AZ Series Equipped



The Rack and Pinion System **L** Series Simplifies Compact, High-Power Linear Motion.

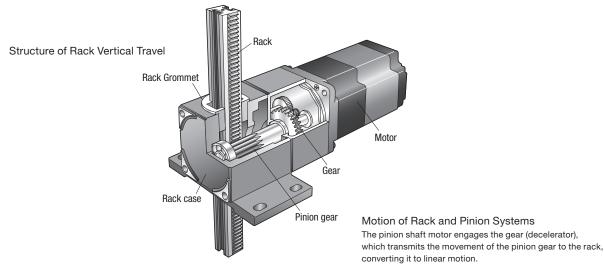
The **L** series is a linear actuator in which a rack and pinion mechanism and a motor have been combined.

The motor is equipped with the *Q_step* **AZ** Series that utilizes a battery-free absolute sensor, which allows for high positioning accuracy and high-load transportation up to 100 kg (220 lb.).

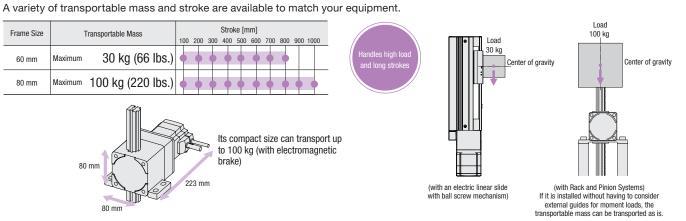
Easy to Use Linear Motion Mechanism that is "Compact" and "High Strength"

The Rack and Pinion System can easily convert the motor's rotation to linear motion.

The linear motion mechanism has a compact design but it can transport large loads due to its high-strength fabrication.

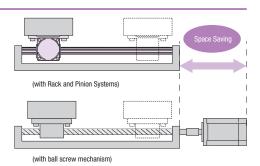


Vertical Operation Can Handle a Max. Transportable Load of 100 kg (220 lb.) and a Max. Stroke of 1000 mm (39.3 in.)



Space Saving

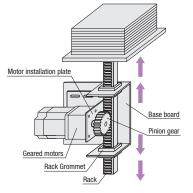
The body is able to move automatically by fixing the screw holes on both ends of the rack. It is effective in large equipment in which motor space is limited.



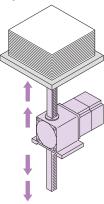


The Rack and Pinion System can reduce the number of parts used, and it can also significantly reduce the time spent on design and assembly.

If Parts are Purchased Separately



With Rack and Pinion Systems



Setting in Millimeter Increments

The drive motor is equipped with the QSTEP AZ Series hybrid control system. By combining with the MEXEO2* support software, the linear motion can be easily set in millimeter increments, which allows for various linear motion applications.

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AZ Series Pulse Input/Bult-In Control +	Operation de	ta i			
Company data		Name	Operation type	Poston (m)	Speed (mm/a)
Operation 1/D event	- 20		incremental pueltoring (based on command position)	0.000	1.000
Extended operation data set	21		incremental postioning (based on command postion)	0.000	1.000
Fearer	#2		Incremental postioning based on command postion)	0.000	1.000
Base settings Motor & Nechanism Coordin	#3		Incremental postioning (based on command postion)	0.000	1.000
ETO & Alam & Info	84		Incremental postioning (based on command postion)	0.000	1.000
-1/O ection and function	25		Incremental positioning (based on command position)	0.000	1.000
Direct-INfunction	38		Incremental positioning (based on command position)	0.000	1.000
Penote-LO function(R4O)	#7		Incremental positioning Based on command position)	0.000	1.000
	- 22		Incremental positioning Based on command position)	0.000	1.000

[Minimum Travel Amount] High-speed type 0.01 mm High transportable mass type 0.001 mm

[Permissible Speed Range]

- 0~500 mm/s (High-speed type)
- $0{\sim}90$ mm/s (High transportable mass type, frame size 60 mm)
- $0\sim$ 40 mm/s (High transportable mass type, frame size 80 mm)

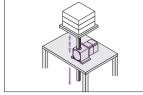
*The MEXEO2 support software can be downloaded from the Oriental Motor website.

What is Hybrid Control System QSTEP?

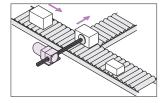
X STEP is a stepper motor-based motor that can perform independent control in which the advantages of "closed loop control" and "open loop control" are combined. It can constantly monitor the motor's position, and it automatically switches between the two control system in response to the situation. It is usually driven in synchronization with the command using open loop control, which enhances its high-response capability. In an overload situation, it corrects the motor's position using closed loop control to continue operation. It is a motor that is easy to use and is also reliable.

Applications

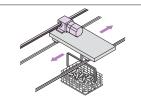
The Rack and Pinion Systems have many applications and they are easy to use.



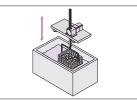
They also make vertical operation easy. Types with an electromagnetic brake are also available for vertical loads.



The high thrust force also makes push-and-pull operations easy.



A wide variety of strokes and speeds are available.



Using the screw holes on both ends of the rack can simplify bolting loads and securing the rack.

Please see the separate catalog for the *Aster* AZ Series product line-up. To select a product, refer to the separate catalog, or see our website.

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Easy Home Setting and Return-to-Home with an Absolute System Equipped with the *Aster* AZ Series Hybrid Control **System** *Aster* **AZ** Series

A compact mechanical multi-turn absolute sensor (patented) has been developed. This can help improve productivity and reduce costs.

No Home Sensor Required

Because it is an absolute system, no home sensor is required.

High-Speed Return-to-Home Operation

Because return-to-home is possible without using a home sensor, return-to-home can be performed at high speed without taking the specifications for sensor sensitivity into account, allowing for a shortened machine cycle.

Reduced Cost

Sensor and wiring costs can be reduced, allowing for lower system costs.

Simple Wiring

Wiring is simplified, and the degree of freedom for equipment design is increased.

Not Affected by Sensor Malfunctions

No need to worry about sensor malfunctions, sensor damage or sensor disconnection.

Improved Return-to-Home Accuracy

Home position accuracy is increased because the return-to-home action is performed regardless of any variations in home sensor sensitivity.

*If no limit sensor is installed, movements that exceed the limit values can be avoided through the use of the limits in the driver software.

Easy Home Position Setting

The home position can be easily set by pressing a switch on the front of the driver, which is saved by the absolute sensor. In addition, home setting is possible with the **MEXEO2** support software or by using an external input signal.



Equipped with Battery-free Absolute Sensor



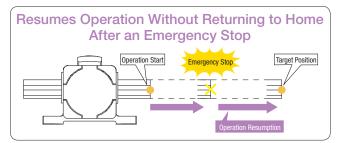
Built-in battery-free absolute sensor constantly monitors the motor's positional information without an external sensor. High Reliability with Closed Loop Control · High Efficiency Technology Reduces Motor Heat Generation and Saves Energy

Return-to-Home Not Required

(Built-in controller type)

If the power shuts down during a positioning operation, the positioning information is retained. Furthermore, for built-in controller types, positioning operations can restart without a return-to-home when recovering from an emergency stop or a blackout.

Battery-free Absolute Sensor



Battery-Free

No battery is required because it is a mechanical-type sensor. Because positioning information is managed mechanically by the absolute sensor, the positioning information can be preserved, even if the power turns off, or if the cable between the motor and the driver are disconnected.

Reduced Maintenance

Because there's no battery that needs replacing, maintenance time and costs can be reduced.

Unlimited Driver Installation Possibilities

Because there is no need to secure space for battery replacement, there are no restrictions on the installation location of the driver, improving the flexibility and freedom of the layout design of the control box.

Safe for Overseas Shipping

With normal batteries that self-discharge, care must be taken when the equipment requires a long shipping time, such as when being sent overseas. The absolute sensor does not require a battery, so there is no limit to how long the positioning information is maintained. In addition, there's no need to worry about various safety regulations, which must be taken into consideration when shipping a battery overseas.

Position Holding Even When the Cable Between the Motor and Driver is Detached

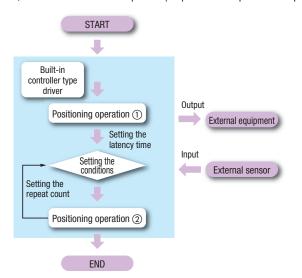
Positioning information is stored within the absolute sensor.

The sequence function simplifies programs

(Available only on the built-in position function type)

By importing output signals for controlling other equipment or external input signals such as those from sensors, the **AZ** Series type can simplify sequence control programs.

No. of positioning operation data items that can be set (up to 256 points)
 No. of general-purpose I/O points (9 points for input and 6 points for output)
 No, of communication I/O points (16 points for input and 16 points for output)



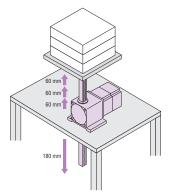
Examples of Loop Function-Assisted Operation

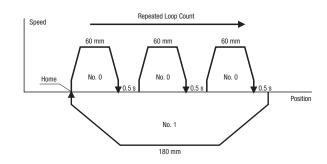
A loop function is a function in which the operation of the linked operation data number is repeated according to the set number of times.

Rack and Pinion Motor Product Name: **LM2F500AZMC-2** Driver Product Name: **AZD-AD** Application: Hoisting buckets

Operating Condition: Return to home after repeating 60 mm travel and 0.5 second stop three times.

Would like a simple method without using PLC.





Example of **MEXEO2** Support Software Setting

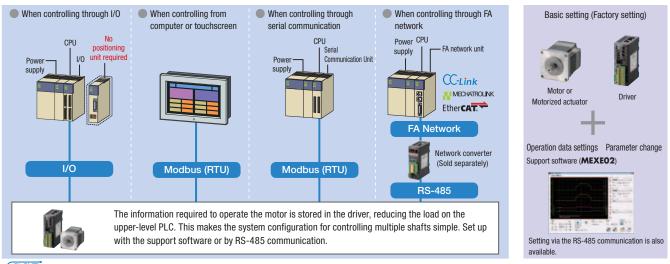
Speed and travel amount are set as "Operating Data".

Operating Data

	Name	Operation type	Position [mm]	Speed [mm/s]	Acc	ment [%]	Drive-complete delay time [s]	Link	Ne	th	Loop count	Loop offset	Loop end No
#0		Incremental positioning (based on command position)	60.00	60.00		0	0.500	Automatic Sequential	}	{	loop 3{	0.00)L-End
#1		Absolute positioning	0.00	60.00) b	0.000	No link	}	2	- \	0.00	•2
			,	Traveling Amount	0-#		Chur Ti	ne Setting)	,		Repetition Co	

Built-in Controller Type

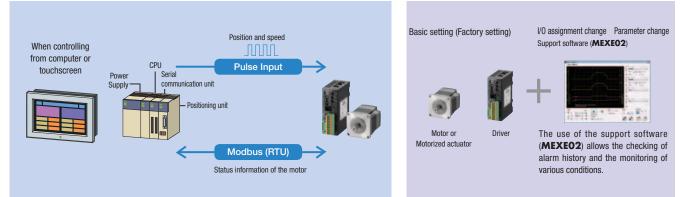
Set the operating data in the driver, and the operating data is selected and executed from the host system. Host system connection and control is performed through I/O, Modbus (RTU), RS-485 communication, or FA network. The use of a network converter (sold separately) allows control via CC-Link communication, MECHATROLINK communication, or EtherCAT communication.



FLEX is a general term of the products that support I/O control, Modbus (RTU) control, and FA network control via a network converter.

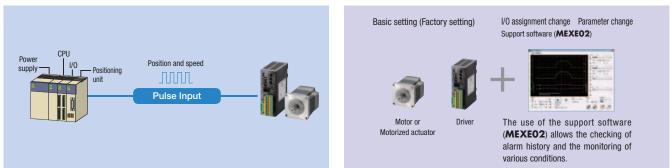
Pulse Input Type with RS-485 Communication

This type executes operation by inputting pulses to the driver. The motor is controlled from the positioning unit (pulse oscillator) provided by the customer. The use of RS-485 communication allows the monitoring of status information (position, speed, torque, alarms, temperature, etc.) of the motor.



Pulse Input Type

This type executes operation by inputting pulses to the driver. The motor is controlled from the positioning unit (pulse oscillator) provided by the customer. The use of the support software (**MEXEO2**) allows the checking of alarm history and the monitoring of various conditions.



CC-Link and WMECHATROLINK are the registered trademarks of the CC-Link Partner Association and the MECHATROLINK Members Association, respectively.
 Ethercart is the registered trademark licensed by Beckhoff Automation in Germany.

• The support software (MEXEO2) can be downloaded from the Oriental Motor website. The media is also available (for free).

The support software enables data setting and verification of the actual drive by using a computer.

Support Software (MEXE02)

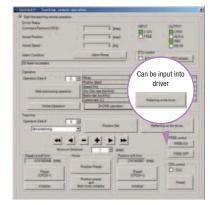
The support software can be downloaded from the website.

Operating Data and

Parameter Settings Setting of operation data and parameters is easily performed via computer. Because the setting data can be saved, when the driver is replaced, the same settings can be used by transferring the saved data.

 Teaching and Remote Operation
 By using the data setting software and manual positioning, the operation command information can be input into the driver. Use when setting up equipment.

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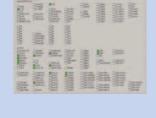
 Multi-monitoring enables remote operation and teaching while monitoring.

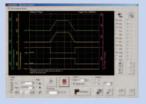
Various Monitoring Functions

I/O Monitoring The state of I/O wiring to the driver can be verified by computer. This can be used for post-wiring I/O checks or I/O checks during operation.

Waveform Monitoring The operational state of the motor (such as command speed and motor load factor), can be checked by an oscilloscope-like image. This can be used for equipment start-up and adjustment.

Alarm Monitoring When an abnormality occurs, the details of the abnormality and the solution can be checked.





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Product Line

Rack and Pinion Motor

часк апо	a Pinion IV	lotor						Driver			
Frame Size	Туре	Electromagnetic Brake	Travel Direc	tion of Rack	Transportable Mass kg. (lbs)	Permissible Speed Range	Stroke [mm]	Туре			
		Drake	Horizontal (B type)	Vertical (F type)	Mass kg. (IDS)	[mm/s]					
	High-Speed				7 (15.4)	0~500		Built-in Controller			
00	Туре					10 (22)	0~250	400 000			
60 mm	High Transportable Mass Type Blank			ľ		30	30	30	30 (cc) 0~90	100~800	Single-phase 100 - 120 VAC Single-Phase/Three- Phase 200-240 VAC
		(66)		(66) 0~90		Pulse Input with RS-485 Communication					
	High-Speed	/Equipped	/Equipped		7 (15.4)	0~500					
90 mm	Туре					0~250	100~1000	Single-phase 100 - 120 VAC Single-Phase/Three- Phase 200-240 VAC			
80 mm	High Transportable				70 (154)	0~40	100*~1000	Pulse Input			
	Mass Type				100 (220)	0~20					
	1	1	l	1	1	1		Single phase 100			

Single-phase 100 -120 VAC Single-Phase/Three-Phase 200-240 VAC

How to Read Specifications Table

Specifications

Frame Size			60 mm	80 mm
	Standard			
Actuator Product Name	with Electromagnetic Brake	ea	LM2_500AZMC-	LM4_500AZMC-
	Built-in Controller Type		AZD-AD (Single-Phase 100-120 VAC), AZD	-CD (Single-Phase/Three-Phase 200-240 VAC)
Driver Product Name	Pulse Input Type with RS-4	85 Communication	AZD-AX (Single-Phase 100-120 VAC), AZD	-CX (Single-Phase/Three-Phase 200-240 VAC)
	Pulse Input Type		AZD-A (Single-Phase 100-120 VAC), AZD	-C (Single-Phase/Three-Phase 200-240 VAC)
Equipped Motor (AZ Series	3)		AZM	M66
D— Maximum Speed		mm/s	50	20
2 — Transportable Mass		kg	10 (250 mm/s) 7 (500 mm/s)	20 (250 mm/s) 7 (500 mm/s)
3 Maximum Acceleration		m/s ²	1	1
4)— Thrust*1		Ν	110 (250 mm/s) 77 (500 mm/s)	220 (250 mm/s) 77 (500 mm/s)
5— Push Force		N	110	220
6)— Holding Force	Power On	N	110	220
	with Electromagnetic Brake	e N	110	220
D— Minimum Travel Amount		mm	0.	01
8 — Rotor Inertia		J: kg⋅m²	370> (530×	
9)— Stroke		mm	100, 200, 300, 400, 500, 600, 700, or 800	100, 200, 300, 400, 500, 600, 700, 800, 900, or 1000
	Voltage and Frequency		Single-Phase 100-120 VAC, Single-Phase/Three	ee-Phase 200-240 VAC -15 to +6% 50/60Hz
Dowor Supply Input	land Command	Single-Phase 100-120 VAC	3.	.8
Power Supply Input	Input Current A	Single-Phase 200-240 VAC	2	.3
	n	Three-Phase 200-240 VAC	1.	
Control Power Supply			24 VDC±5%*3	0.25 A (0.5 A)*2

• Either **F** (vertical to the mounting foot surface) or **B** (horizontal to the mounting foot surface) indicating the rack moving direction is entered where the box is located within the product name. A number indicating the rack stroke is entered where the box is located within the product name.

When the rack is moved in the vertical direction, the load mass that can be driven is the value obtained by subtracting the rack mass from the transportable mass. Refer to 'Dimensions' for the rack

mass.

\$1 For a value obtained by adding the acceleration thrust of a load to the load thrust, do not exceed the thrust amount.

*2 The bracket () indicates the value for the product with an electromagnetic brake.

*3 For the type with an electromagnetic brake, a 24 VDC±4% specification applies if the wiring distance between the motor and the driver is extended to 20 m using a cable.

Depending on the product, limitations and caution may be required for usage. For details, refer to the notes on each product page.

Maximum Speed

Maximum speed allowed when transporting the transportable mass.

②Transportable Mass

Mass that can be moved under operating performance of the rack and pinion motor.

③Maximum Acceleration

The maximum acceleration allowed when the transportable mass is transferred.

④Thrust

Force from the rack that pushes the load when speed is constant.

⑤Push Force

The pressure applied to the load during the pushing operation.

6 Holding Force

Holding force when the motor is stopped or when the electromagnetic brake is operating, while power is supplied.

⑦Minimum Travel Amount

The minimum distant that the rack travels. (Factory setting)

⑧Rotor Inertia

This refers to the inertia of the rotor inside the motor.

(9)Stroke

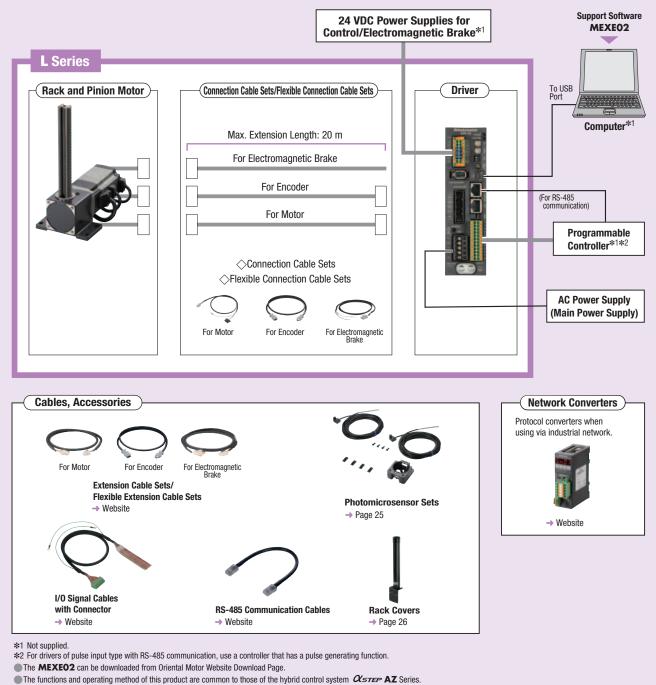
The maximum distance the rack can be pushed and pulled.

System Configuration

Combination of L Series with Electromagnetic Brake and either Built-in Controller Type Driver or Pulse Input Type Driver with RS-485 Communication

This is an example of a configuration using I/O control or RS-485 communication in a built-in controller type driver.

Rack and pinion motors, drivers, and connection cable sets/flexible connection cable sets need to be ordered separately.



The functions and operating method of this product are common to those of the hybrid control system XSTEP AZ Series. For the functions and operating method of this product, refer to the operating manuals (Driver Edition and Function Edition) of the AZ Series. The OPERATING MANUAL Driver Edition is included in the product, but the OPERATING MANUAL Function Edition is not included. For detail, contact the nearest Oriental Motor sales office or download from Oriental Motor Website Download Page. https://www.orientalmotor.com

•Example of System Configuration Pricing

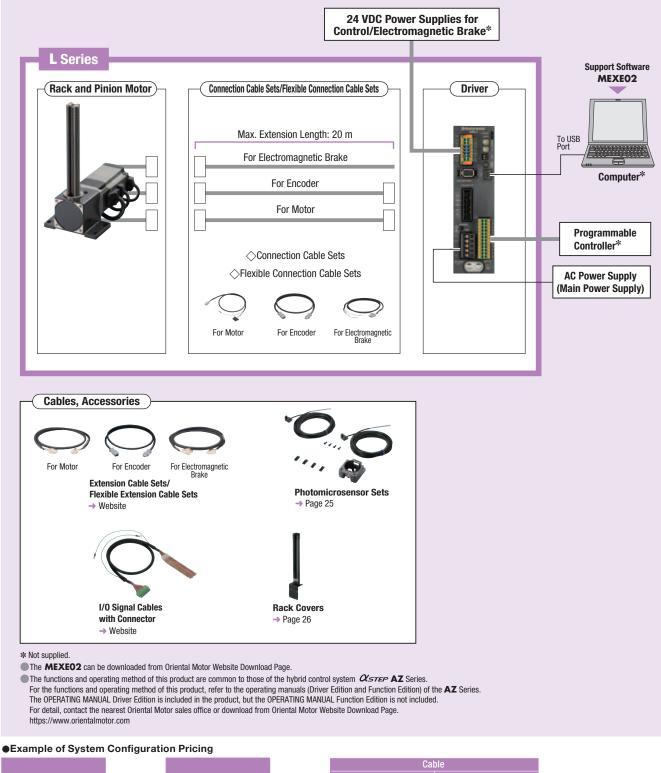


The system configuration shown above is an example. Other combinations are also available.
 Note

The motor cable and electromagnetic brake cable from the motor cannot be connected directly to the driver. When connecting to a driver, use a connection cable.

Combination of L Series with Electromagnetic Brake and Pulse Input Type Driver

This is an example of a single-axis system configuration using a programmable controller (with pulse generating function). Rack and pinion motors, drivers, and connection cable sets/flexible connection cable sets need to be ordered separately.





• The system configuration shown above is an example. Other combinations are also available.

Note

• The motor cable and electromagnetic brake cable from the motor cannot be connected directly to the driver. When connecting to a driver, use a connection cable.

Product Number Code

Rac	k and	d Pi	nion Moto	ors			
LM	4	F	500	AZ	M	С	- 1
1	2	3	4	5	6	7	8

1	Series Name	LM: L Series Rack and Pinion Motor
2	Frame Size	2 : 60 mm 4 : 80 mm
3	Moving Direction of Rack	F: Vertical to Mounting Foot Surface B: Horizontal to Mounting Foot Surface
4	Rack Maximum Speed	40 : 40 mm/s 90 : 90 mm/s 500 : 500 mm/s
5	Equipped Motor	AZ: AZ Series
6	Motor Shaft Features	A: Standard M: with Electromagnetic Brake
0	Motor Specifications	C: AC Power Supply Input Specifications
8	Stroke	1: 100 mm 2: 200 mm 3: 300 mm 4: 400 mm 5: 500 mm 6: 600 mm 7: 700 mm 8: 800 mm 9: 900 mm 10: 1000 mm 10: 1000 mm 10: 1000 mm

1	Driver Type	AZD: AZ Series Driver
2	Power Supply Input	A: Single-Phase 100-120 VAC C: Single-Phase/Three-Phase 200-240 VAC
3	Туре	D: Built-in Controller Type X: Pulse Input Type with RS-485 Communication Blank: Pulse Input Type

Connection Cable Sets/Flexible Connection Cable Sets



Drivers

AZD - C D

1 2 3

1		CC: Cable			
2	Length	005: 0.5 m 010: 1 m 015: 1.5 m 020: 2 m 025: 2.5 m 030: 3 m 040: 4 m 050: 5 m 070: 7 m 100: 10 m 150: 15 m 200: 20 m			
3	Reference Number				
4	Applicable Model	Z: AZ Series			
5	Cable Type	F: Connection Cable Set R: Flexible Connection Cable Set			
6	Electromagnetic Brake	Blank: without Electromagnetic Brake B: with Electromagnetic Brake			

Product Line

Rack and Pinion Motors



Frame Size	Product Name	List Price
	LM2_500AZAC-1	\$788.00
	LM2_500AZAC-2	\$794.00
	LM2 500AZAC-3	\$794.00
00	LM2_500AZAC-4	\$799.00
60 mm	LM20500AZAC-5	\$805.00
	LM2_500AZAC-6	\$817.00
	LM20500AZAC-7	\$840.00
	LM2_500AZAC-8	\$886.00
	LM4_500AZAC-1	\$838.00
	LM4_500AZAC-2	\$844.00
	LM4_500AZAC-3	\$844.00
	LM4_500AZAC-4	\$850.00
80 mm	LM4_500AZAC-5	\$850.00
00 11111	LM4_500AZAC-6	\$861.00
	LM4_500AZAC-7	\$873.00
	LM4_500AZAC-8	\$930.00
	LM4_500AZAC-9	\$953.00
	LM4_500AZAC-10	\$976.00

• Either F (vertical to the mounting foot surface) or B (horizontal to the mounting foot surface) indicating the rack moving direction is entered where the box \square is located within the product name.

\bigcirc High-Transportable-Mass Type



Frame Size	Product Name	List Price
	LM2090AZAC-1	\$805.00
	LM2090AZAC-2	\$811.00
	LM2090AZAC-3	\$811.00
<u> </u>	LM2 90AZAC-4	\$817.00
60 mm	LM2 90AZAC-5	\$822.00
	LM2090AZAC-6	\$834.00
	LM2090AZAC-7	\$857.00
	LM2090AZAC-8	\$903.00
	LM4 40AZAC-1	\$861.00
	LM4 40AZAC-2	\$867.00
	LM4_40AZAC-3	\$867.00
	LM4 40AZAC-4	\$873.00
80 mm	LM4 40AZAC-5	\$873.00
00 11111	LM4_40AZAC-6	\$884.00
	LM4_40AZAC-7	\$896.00
	LM4_40AZAC-8	\$953.00
	LM4_40AZAC-9	\$976.00
	LM4 40AZAC-10	\$999.00

• Either F (vertical to the mounting foot surface) or B (horizontal to the mounting foot surface) indicating the rack moving direction is entered where the box \square is located within the product name.

♦ High-Speed Type with Electromagnetic Brake			
Frame Size	Product Name	List Price	
	LM2_500AZMC-1	\$1,018.00	
	LM2_500AZMC-2	\$1,024.00	
	LM2D500AZMC-3	\$1,024.00	
60 mm	LM2D500AZMC-4	\$1,029.00	
60 11111	LM2_500AZMC-5	\$1,035.00	
	LM2D500AZMC-6	\$1,047.00	
	LM2_500AZMC-7	\$1,070.00	
	LM2D500AZMC-8	\$1,116.00	
	LM4_500AZMC-1	\$1,068.00	
	LM4_500AZMC-2	\$1,074.00	
	LM4_500AZMC-3	\$1,074.00	
	LM4_500AZMC-4	\$1,080.00	
00 mm	LM4_500AZMC-5	\$1,080.00	
80 mm	LM4_500AZMC-6	\$1,091.00	
	LM4_500AZMC-7	\$1,103.00	
	LM4_500AZMC-8	\$1,160.00	
	LM4_500AZMC-9	\$1,183.00	
	LM4_500AZMC-10	\$1,206.00	

• Either **F** (vertical to the mounting foot surface) or **B** (horizontal to the mounting foot surface) indicating the rack moving direction is entered where the box \Box is located within the product name.

◇High-Transportable-Mass Type with Electromagnetic Brake



Electroma		
Frame Size	Product Name	List Price
	LM2_90AZMC-1	\$1,035.00
	LM2 90AZMC-2	\$1,041.00
	LM2 90AZMC-3	\$1,041.00
60 mm	LM2_90AZMC-4	\$1,047.00
00 11111	LM2_90AZMC-5	\$1,052.00
	LM2_90AZMC-6	\$1,064.00
	LM2_90AZMC-7	\$1,087.00
	LM2_90AZMC-8	\$1,133.00
	LM4_40AZMC-1	\$1,091.00
	LM4_40AZMC-2	\$1,097.00
	LM4_40AZMC-3	\$1,097.00
	LM4_40AZMC-4	\$1,103.00
80 mm	LM4_40AZMC-5	\$1,103.00
0011111	LM4_40AZMC-6	\$1,114.00
	LM4_40AZMC-7	\$1,126.00
	LM4_40AZMC-8	\$1,183.00
	LM4_40AZMC-9	\$1,206.00
	LM4_40AZMC-10	\$1,229.00

● Either **F** (vertical to the mounting foot surface) or **B** (horizontal to the mounting foot surface) indicating the rack moving direction is entered where the box □ is located within the product name.

Drivers

◇Built-in Controller Type

Power Supply Input	Product Name	List Price
Single-Phase 100-120 VAC	AZD-AD	\$588.00
Single-Phase/Three-Phase 200-240 VAC	AZD-CD	\$588.00

◇Pulse Input Type		
Power Supply Input	Product Name	List Price
Single-Phase 100-120 VAC	AZD-A	\$531.00
Single-Phase/Three-Phase 200-240 VAC	AZD-C	\$531.00

Connection Cable Sets/Flexible Connection Cable Sets

Use a flexible connection cable set if the cable will be bent.

The motor cable and electromagnetic brake cable from the motor cannot be connected directly to the driver. When connecting to a driver, use a connection cable.

1

◇For Motor/Encoder			
			For Motor For Encoder
Product Line	Length L (m)	Product Name	List Price
	0.5	CC005VZF	\$35.00
	1	CC010VZF	\$35.00
	1.5	CC015VZF	\$43.00
	2	CC020VZF	\$50.00
	2.5	CC025VZF	\$56.00
Connection Cable	3	CC030VZF	\$62.00
Sets	4	CC040VZF	\$97.00
	5	CC050VZF	\$110.00
	7	CC070VZF	\$136.00
	10	CC100VZF	\$176.00
	15	CC150VZF	\$243.00
	20	CC200VZF	\$310.00
	0.5	CC005VZR	\$84.00
	1	CC010VZR	\$84.00
	1.5	CC015VZR	\$91.00
	2	CC020VZR	\$99.00
	2.5	CC025VZR	\$105.00
Flexible Connection Cable	3	CC030VZR	\$111.00
Sets	4	CC040VZR	\$125.00
0010	5	CC050VZR	\$141.00
	7	CC070VZR	\$180.00
	10	CC100VZR	\$236.00
	15	CC150VZR	\$332.00
	20	CC200VZR	\$426.00

\square	
\sim	◇For Motor/Encoder/
For Encoder	Electromagnetic Bra

◇Pulse Input Type with RS-485 Communication

Power Supply Input

Single-Phase 100-120 VAC

Single-Phase/Three-Phase 200-240 VAC

>For Motor/E			
Electromagnetic Brake		For Motor For Encoder	For Electromagnetic Brak
Product Line	Length L (m)	Product Name	List Price
	0.5	CC005VZFB	\$52.00
	1	CC010VZFB	\$52.00
	1.5	CC015VZFB	\$60.00
	2	CC020VZFB	\$67.00
	2.5	CC025VZFB	\$74.00
Connection Cable	3	CC030VZFB	\$82.00
Sets	4	CC040VZFB	\$120.00
	5	CC050VZFB	\$135.00
	7	CC070VZFB	\$166.00
	10	CC100VZFB	\$213.00
	15	CC150VZFB	\$293.00
	20	CC200VZFB	\$372.00
	0.5	CC005VZRB	\$114.00
	1	CC010VZRB	\$114.00
	1.5	CC015VZRB	\$123.00
ĺ	2	CC020VZRB	\$134.00
	2.5	CC025VZRB	\$142.00
Flexible Connection Cable	3	CC030VZRB	\$151.00
Sets	4	CC040VZRB	\$170.00
0613	5	CC050VZRB	\$191.00
	7	CC070VZRB	\$240.00
	10	CC100VZRB	\$311.00
	15	CC150VZRB	\$432.00
	20	CC200VZRB	\$551.00

Included

Rack and Pinion Motors

Type	Operating Manual
Common to All Types	1 Сору

Drivers

Type	Connector	Operating Manual
Common to All Types	CN4 Connector (1 pc.) CN1 Connector (1 pc.) CN5 Connector (1 pc.) Connector Lever (1 pc.)	1 Сору

Connection Cable Sets/Flexible Connection Cable Sets

Included Type	Operating Manual
Connection Cable Set	-
Flexible Connection Cable Set	1 Сору

Please see the separate catalog for the *Xstep* AZ Series product line-up. To select a product, refer to the separate catalog, or see our website.





List Price

\$588.00

\$588.00

Product Name

AZD-AX

AZD-CX

K

High-Speed Type

Specifications

Frame Size			60 mm	80 mm	
Actuator Draduat Nama	Standard		LM2 500AZAC-	LM4_500AZAC-	
Actuator Product Name	with Electromagnetic Brake		LM2_500AZMC-	LM4_500AZMC-	
	Built-in Controller Type		AZD-AD (Single-Phase 100-120 VAC), AZD	-CD (Single-Phase/Three-Phase 200-240 VAC)	
Driver Product Name	Pulse Input Type with RS-48	5 Communication	AZD-AX (Single-Phase 100-120 VAC), AZD	-CX (Single-Phase/Three-Phase 200-240 VAC)	
	Pulse Input Type		AZD-A (Single-Phase 100-120 VAC), AZD	-C (Single-Phase/Three-Phase 200-240 VAC)	
Equipped Motor (AZ Series)			AZI	M66	
Maximum Speed		mm/s	5	00	
Transportable Mass	ortable Mass kg		10 (250 mm/s) 7 (500 mm/s)	20 (250 mm/s) 7 (500 mm/s)	
Maximum Acceleration		m/s ²	1		
Thrust*1		Ν	110 (250 mm/s) 77 (500 mm/s)	220 (250 mm/s) 77 (500 mm/s)	
Push Force		N	110	220	
Helding Fores	Power On	Ν	110	220	
Holding Force	with Electromagnetic Brake	Ν	110	220	
Minimum Travel Amount mm		0.01			
Rotor Inertia J: kg·m ²		2 370×10 ⁻⁷ (530×10 ⁻⁷)*2			
Stroke		mm	100, 200, 300, 400, 500, 600, 700, or 800	100, 200, 300, 400, 500, 600, 700, 800, 900, or 1000	
	Voltage and Frequency		Single-Phase 100-120 VAC, Single-Phase/Three-Phase 200-240 VAC -15 to +6% 50/60Hz		
	Single-Phase 100-120 VAC		3.8		
Power Supply Input	Input Current A	Single-Phase 200-240 VAC	2	.3	
	A	Three-Phase 200-240 VAC	1.4		
Control Power Supply			24 VDC±5%*3 0.25 A (0.5 A)*2		

• Either F (vertical to the mounting foot surface) or B (horizontal to the mounting foot surface) indicating the rack moving direction is entered where the box 🗌 is located within the product name.

A number indicating the rack stroke is entered where the box 🔲 is located within the product name.

• When the rack is moved in the vertical direction, the load mass that can be driven is the value obtained by subtracting the rack mass from the transportable mass. Refer to 'Dimensions' for the rack mass.

*1 For a value obtained by adding the acceleration thrust of a load to the load thrust, do not exceed the thrust amount.

*2 The bracket () indicates the value for the product with an electromagnetic brake.

*3 For the type with an electromagnetic brake, a 24 VDC±4% specification applies if the wiring distance between the motor and the driver is extended to 20 m (65.7 ft.) using a cable.

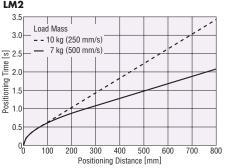
LM4

Positioning Distance – Positioning Time

The positioning time (reference) can be checked from the positioning distance.

The positioning time differs depending on the transportable mass.





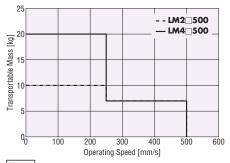
Repetitive Positioning Accuracy (Reference Value)

It is the value measured with the transportable mass. It varies depending on load, driving condition or mounting direction.

	J	<u> </u>
Product Name	Rack Moving Direction	Repetitive Positioning Accuracy [mm]
LM2	Horizontal	+0.25
LM4	Direction	10.25
LM2	Vertical	+0.07
LM4	Direction	±0.07

Load Mass - 20 kg (250 mm/s) 7 kg (500 mm/s) Positioning Time [s] 0<u>k</u> 300 400 500 600 700 800 900 1000 100 200 Positioning Distance [mm]

Operating Speed – Transportable Mass



Notes

The operating speed-transportable mass characteristics shows the data based on Oriental Motor's measurement conditions. If conditions change, the characteristics may change.

• Depending on the driving conditions, a considerable amount of heat may be generated by the motor. To protect the absolute sensor, ensure that the motor case temperature is $80^{\circ}C$ (176°F) or less. (When conforming to the UL Standards, it is required to keep the temperature of the motor case at 75°C (167°F) or less, since the motor is recognized as insulation class A.)

High-Transportable-Mass Type

Specifications

Frame Size			60 mm	80 mm	
A shushes Desidual Marsa	Standard		LM2 90AZAC-	LM4 40AZAC-	
Actuator Product Name	with Electromagnetic Brake		LM2_90AZMC-	LM4_40AZMC-	
	Built-in Controller Type		AZD-AD (Single-Phase 100-120 VAC), AZD	-CD (Single-Phase/Three-Phase 200-240 VAC)	
Driver Product Name	Pulse Input Type with RS-48	35 Communication	AZD-AX (Single-Phase 100-120 VAC), AZD	-CX (Single-Phase/Three-Phase 200-240 VAC)	
Pulse Input Type			AZD-A (Single-Phase 100-120 VAC), AZD	-C (Single-Phase/Three-Phase 200-240 VAC)	
Equipped Motor (AZ Series)			AZ	M66	
Maximum Speed		mm/s	90	40	
Transportable Mass		kg	30	100 (20 mm/s) 70 (40 mm/s)	
Maximum Acceleration		m/s ²	0.187	0.074	
Thrust*1		Ν	306	1008 (20 mm/s) 705 (40 mm/s)	
Push Force		N	306	1008	
Holding Force	Power On	Ν	306	1008	
Holding Force	with Electromagnetic Brake	N	306	1008	
Minimum Travel Amount		mm	0.0	001	
Rotor Inertia		J: kg⋅m²		×10 ⁻⁷ 10 ⁻⁷)*2	
Stroke		mm	100, 200, 300, 400, 500, 600, 700, or 800	100, 200, 300, 400, 500, 600, 700, 800, 900, or 1000	
	Voltage and Frequency		Single-Phase 100-120 VAC, Single-Phase/Three-Phase 200-240 VAC -15 to +6% 50/60Hz		
Dowor Cupply Ippyt		Single-Phase 100-120 VAC	3	.8	
Power Supply Input	Input Current A	Single-Phase 200-240 VAC	2	.3	
	A	Three-Phase 200-240 VAC	1.4		
Control Power Supply			24 VDC±5%*3	0.25 A (0.5 A)*2	

• Either F (vertical to the mounting foot surface) or B (horizontal to the mounting foot surface) indicating the rack moving direction is entered where the box 🗌 is located within the product name.

A number indicating the rack stroke is entered where the box 🔲 is located within the product name.

• When the rack is moved in the vertical direction, the load mass that can be driven is the value obtained by subtracting the rack mass from the transportable mass. Refer to 'Dimensions' for the rack mass.

Load Mass

- 100 kg (20 mm/s)

70 kg (40 mm/s)

*1 For a value obtained by adding the acceleration thrust of a load to the load thrust, do not exceed the thrust amount.

*2 The bracket () indicates the value for the product with an electromagnetic brake.

*3 For the type with an electromagnetic brake, a 24 VDC±4% specification applies if the wiring distance between the motor and the driver is extended to 20 m (65.7 ft.) using a cable.

LM4

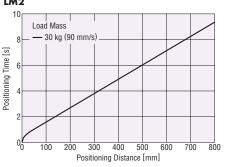
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Positioning Distance – Positioning Time

The positioning time (reference) can be checked from the positioning distance.

The positioning time differs depending on the transportable mass.





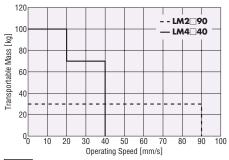
Positioning Time [s] 05 05 0 100 200 300 400 500 600 700 800 900 1000 Positioning Distance [mm]

Repetitive Positioning Accuracy (Reference Value)

It is the measured value with transportable mass. It varies depending on load, driving condition or mounting direction.

Product Name	Rack Moving Direction	Repetitive Positioning Accuracy [mm]						
LM2	Horizontal	+0.25						
LM4	Direction	0.25						
LM2 Vertical		10.07						
LM4	Direction	±0.07						

Operating Speed – Transportable Mass



Notes

The operating speed-transportable mass characteristics shows the data based on Oriental Motor's measurement conditions. If conditions change, the characteristics may change,

Depending on the driving conditions, a considerable amount of heat may be generated by the motor. To protect the absolute sensor, ensure that the motor case temperature is 80°C (176°F) or less. (When conforming to the UL Standards, it is required to keep the temperature of the motor case at 75°C (167°F) or less, since the motor is recognized as insulation class A.)

Electromagnetic Brake Specifications

Product Name		LM2	LM4		
Brake Type		Power Off Activated Type			
Power Supply Voltage		24 VDC	±5% *		
Power Supply Current	Α	0.:	25		
Brake Operating Time	ms	2	0		
Brake Releasing Time	ms	3	0		
Time Rating		Conti	nuous		

*For the type with an electromagnetic brake, a 24 VDC±4% specification applies if the wiring distance between the motor and the driver is extended to 20 m using a cable.

General Specifications

AV°*1 C €*1

			Driver			
		Rack and Pinion Motor	Built-in Controller Type Pulse Input Type with RS-485 Communication	Pulse Input Type		
Thermal Class		130 (B) [UL Recognized 105 (A)]	-			
100 MΩ or more when a 500 VDC megger is applied between the following places: 100 MΩ or more when a 500 VDC megger is applied between the following · Protective Earth Terminal – Power Supply Terminal · Encoder Connector – Power Supply Terminal · Los e – Electromagnetic Brake Windings*2						
Dielectric Strength · Case – Motor Windings 1.5 kVAC, 50 Hz or · Case – Electromagnetic Brake Windings*2		Sufficient to withstand the following for 1 minute: · Case – Motor Windings 1.5 kVAC, 50 Hz or 60 Hz · Case – Electromagnetic Brake Windings*2 1.5 kVAC, 50 Hz or 60 Hz	Sufficient to withstand the following for 1 minute: • Protective Earth Terminal – Power Supply Terminal 1.5 kVAC, 50 Hz or 60 Hz • Encoder Connector – Power Supply Terminal 1.8 kVAC, 50 Hz or 60 Hz • I/O Signal Terminal – Power Supply Terminal 1.8 kVAC, 50 Hz or 60 Hz			
Operating	Ambient Temperature	0 to +40°C (Non-freezing) ^{%3} (+32 ~ +104°F)	0 to +55°C (Non-freezing) ^{*4} (+32 ~ +131°F)			
Environment	Ambient Humidity	85% or less (Non-condensing)				
	Atmosphere	No corrosive gases or dust. The	product should not be exposed to water, oil or ot	ner liquids.		
Degree of Protection		IP30 (Excluding rack moving part and connector part)	IP10	IP20		
Rotation Detection Range in Power OFF State (Motor Output Shaft)		±900 Rotations (1800 Rotations)				

*1 The motor product name (not the actuator product name) is recognized by UL under the UL Standards.

The motor product name (not the actuator product name) conforms to the standards to affix the CE Marking.

*2 Only for products with an electromagnetic brake.

 $\ensuremath{\ast}3$ It is based on Oriental Motor's measurement conditions.

*4 When installing a motor to a heat sink of a capacity at least equivalent to an aluminum plate, (200×200 mm), thickness 2 mm.

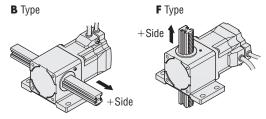
Note

• Disconnect the motor and driver when taking an insulation resistance measurement or performing a dielectric voltage withstand test.

Also, do not perform these tests on the absolute sensor part of the motor.

Moving Direction

At the time of shipment, the moving direction of the rack is set as follows.



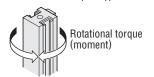
Please see the separate	Oriestalmotor AZ Series
catalog for the <i>Xster</i> AZ	
Series product line-up.	<i>USTEP</i>
To select a product, refer to	
the separate catalog, or see	
our website.	

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Rack Permissible Rotational Torque (Moment)

Product Name	Rack Permissible Rotational Torque (Moment)
LM2	0.3 N·m max.
LM4	0.5 N·m max.

Keep the rotational torque below the permissible value. If the rotational torque is applied too much, the rack bushing will wear in a short time.



Permissible Radial Load

Stroke mm	LM2□90	LM2□500	LM4□40	LM4□500
100	25	25*1	120	60* ¹
200	20	20 ^{*1}	90	40 ^{*1}
300	10	10*1	70	30* ¹
400	10	10 ^{*1}	60	25 ^{*1}
500	7	7 * 1	50	20* ¹
600	*2	*2	40	15*1
700	*2	*2	40	10*1
800	*2	*2	25	7* ¹
900	-	-	20	*2
1000	_	_	15	*2

• Either F (vertical to the mounting foot surface) or B (horizontal to the mounting foot surface) indicating the rack moving direction is entered where the box is located within the product name. *1 The value is the operation speed up to 90 mm/s. When operating at a speed exceeding 90 mm/s, do not apply a radial load to the rack by providing a guide, etc.. *2 Do not apply a radial load to the rack by providing a guide, etc. as the rack may be damaged.



Dimensions (Unit: mm)

•LM2 B Type

◇Frame Size 60 mm High-Speed Type

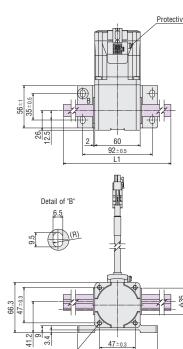
2D & 3D CAD

Stroke mm	Product Name	L1	L2	Mass (Rack Mass Included) kg	Rack Mass kg	2D CAD
100	LM2B500AZAC-1	229.4	132	1.9	0.5	D7818
200	LM2B500AZAC-2	330.0		2.0	0.6	D7819
300	LM2B500AZAC-3	430.4		2.2	0.8	D7820
400	LM2B500AZAC-4	531.0		2.4	1.0	D7821
500	LM2B500AZAC-5	631.5		2.6	1.2	D7822
600	LM2B500AZAC-6	731.4		2.8	1.4	D7823
700	LM2B500AZAC-7	829.5		3.0	1.6	D7824
800	LM2B500AZAC-8	930.4		3.2	1.8	D7825

\Diamond Frame Size 60 mm High-Speed Type with Electromagnetic Brake

2D & 3D CAD

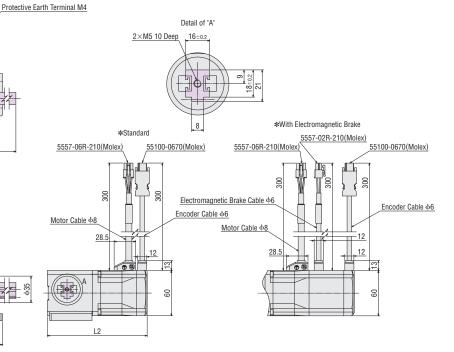
Stroke mm	Product Name	L1	L2	Mass (Rack Mass Included) kg	Rack Mass kg	2D CAD
100	LM2B500AZMC-1	229.4	178	2.2	0.5	D7826
200	LM2B500AZMC-2	330.0		2.3	0.6	D7827
300	LM2B500AZMC-3	430.4		2.5	0.8	D7828
400	LM2B500AZMC-4	531.0		2.7	1.0	D7829
500	LM2B500AZMC-5	631.5		2.9	1.2	D7830
600	LM2B500AZMC-6	731.4		3.1	1.4	D7831
700	LM2B500AZMC-7	829.5	-	3.3	1.6	D7832
800	LM2B500AZMC-8	930.4		3.5	1.8	D7833



106±1

4

4×M6 10 Deep



•LM2 F Type

\bigcirc Frame Size 60 mm High-Speed Type

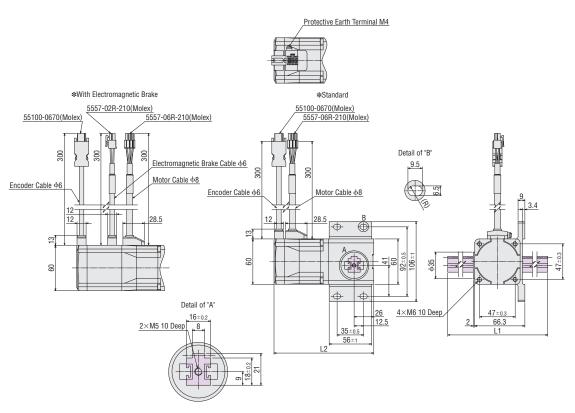
2D & 3D CAD

Stroke mm	Product Name	L1	L2	Mass (Rack Mass Included) kg	Rack Mass kg	2D CAD
100	LM2F500AZAC-1	229.4	132	1.9	0.5	D7786
200	LM2F500AZAC-2	330.0		2.0	0.6	D7787
300	LM2F500AZAC-3	430.4		2.2	0.8	D7788
400	LM2F500AZAC-4	531.0		2.4	1.0	D7789
500	LM2F500AZAC-5	631.5		2.6	1.2	D7790
600	LM2F500AZAC-6	731.4		2.8	1.4	D7791
700	LM2F500AZAC-7	829.5		3.0	1.6	D7792
800	LM2F500AZAC-8	930.4		3.2	1.8	D7793

$\diamondsuit \mbox{Frame Size 60}\ \mbox{mm}$ High-Speed Type with Electromagnetic Brake

2D & 3D CAD

	0 1		0			
Stroke mm	Product Name	L1	L2	Mass (Rack Mass Included) kg	Rack Mass kg	2D CAD
100	LM2F500AZMC-1	229.4		2.2	0.5	D7794
200	LM2F500AZMC-2	330.0		2.3	0.6	D7795
300	LM2F500AZMC-3	430.4		2.5	0.8	D7796
400	LM2F500AZMC-4	531.0	178	2.7	1.0	D7797
500	LM2F500AZMC-5	631.5	1/0	2.9	1.2	D7798
600	LM2F500AZMC-6	731.4		3.1	1.4	D7799
700	LM2F500AZMC-7	829.5		3.3	1.6	D7800
800	LM2F500AZMC-8	930.4		3.5	1.8	D7801



•LM2 B Type

\bigcirc Frame Size 60 mm High-Transportable-Mass Type

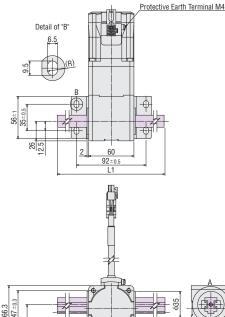
2D & 3D CAD

Stroke mm	Product Name	L1	L2	Mass (Rack Mass Included) kg	Rack Mass kg	2D CAD
100	LM2B90AZAC-1	229.4		2.1	0.5	D7802
200	LM2B90AZAC-2	330.0	170.5	2.2	0.6	D7803
300	LM2B90AZAC-3	430.4		2.4	0.8	D7804
400	LM2B90AZAC-4	531.0		2.6	1.0	D7805
500	LM2B90AZAC-5	631.5		2.8	1.2	D7806
600	LM2B90AZAC-6	731.4		3.0	1.4	D7807
700	LM2B90AZAC-7	829.5		3.2	1.6	D7808
800	LM2B90AZAC-8	930.4		3.4	1.8	D7809

\Diamond Frame Size 60 mm High-Transportable-Mass Type with Electromagnetic Brake

2D & 3D CAD

Stroke mm	Product Name	L1	L2	Mass (Rack Mass Included) kg	Rack Mass kg	2D CAD
100	LM2B90AZMC-1	229.4		2.5	0.5	D7810
200	LM2B90AZMC-2	330.0	216.5	2.6	0.6	D7811
300	LM2B90AZMC-3	430.4		2.8	0.8	D7812
400	LM2B90AZMC-4	531.0		3.0	1.0	D7813
500	LM2B90AZMC-5	631.5	210.5	3.2	1.2	D7814
600	LM2B90AZMC-6	731.4		3.4	1.4	D7815
700	LM2B90AZMC-7	829.5		3.6	1.6	D7816
800	LM2B90AZMC-8	930.4		3.8	1.8	D7817

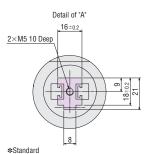


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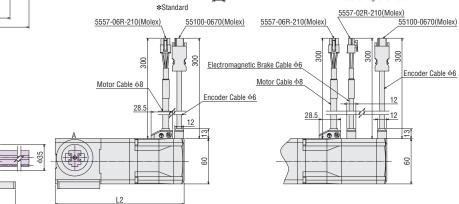
106±1

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4 4×M6 10 Deep







•LM2 F Type

\Diamond Frame Size 60 mm High-Transportable-Mass Type

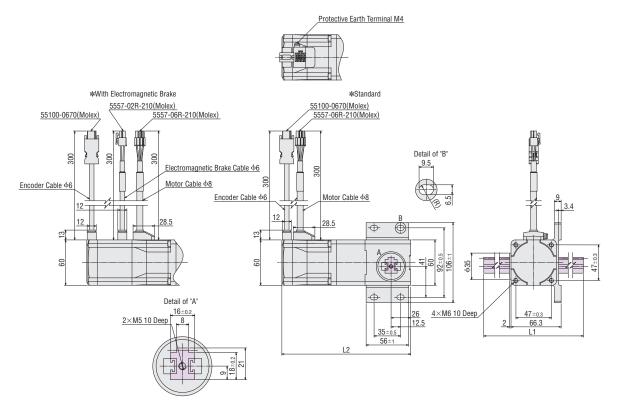
2D & 3D CAD

Stroke mm	Product Name	L1	L2	Mass (Rack Mass Included) kg	Rack Mass kg	2D CAD
100	LM2F90AZAC-1	229.4		2.1	0.5	D7770
200	LM2F90AZAC-2	330.0		2.2	0.6	D7771
300	LM2F90AZAC-3	430.4	170.5	2.4	0.8	D7772
400	LM2F90AZAC-4	531.0		2.6	1.0	D7773
500	LM2F90AZAC-5	631.5	170.5	2.8	1.2	D7774
600	LM2F90AZAC-6	731.4		3.0	1.4	D7775
700	LM2F90AZAC-7	829.5		3.2	1.6	D7776
800	LM2F90AZAC-8	930.4		3.4	1.8	D7777

\Diamond Frame Size 60 mm High-Transportable-Mass Type with Electromagnetic Brake

2D & 3D CAD

	e 1			•		
Stroke mm	Product Name	L1	L2	Mass (Rack Mass Included) kg	Rack Mass kg	2D CAD
100	LM2F90AZMC-1	229.4		2.5	0.5	D7778
200	LM2F90AZMC-2	330.0		2.6	0.6	D7779
300	LM2F90AZMC-3	430.4		2.8	0.8	D7780
400	LM2F90AZMC-4	531.0	216.5	3.0	1.0	D7781
500	LM2F90AZMC-5	631.5	210.5	3.2	1.2	D7782
600	LM2F90AZMC-6	731.4		3.4	1.4	D7783
700	LM2F90AZMC-7	829.5		3.6	1.6	D7784
800	LM2F90AZMC-8	930.4]	3.8	1.8	D7785



•LM4 B Type

◇Frame Size 80 mm

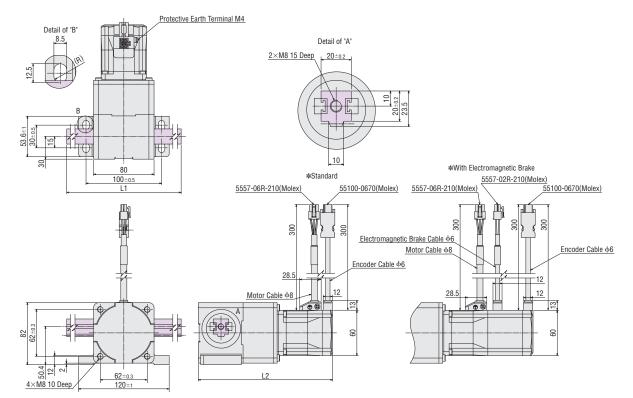
2D & 3D CAD

Stroke	Product Name	e L1 L2		Mass (Rack I	Rack Mass	2D CAD	
mm				High-Speed Type	High-Transportable-Mass Type	kg	
100	LM4B AZAC-1	243.5		2.8	2.9	0.7	D7844
200	LM4B AZAC-2	341.6]	3.1	3.2	1.0	D7845
300	LM4B AZAC-3	443.7	-	3.4	3.5	1.3	D7846
400	LM4B AZAC-4	541.9		3.6	3.7	1.5	D7847
500	LM4B AZAC-5	640.1		3.9	4.0	1.8	D7848
600	LM4B AZAC-6	742.2	177.7	4.2	4.3	2.1	D7849
700	LM4B_AZAC-7	840.4	1	4.5	4.6	2.4	D7850
800	LM4B AZAC-8	942.5		4.8	4.9	2.7	D7851
900	LM4B AZAC-9	1040.7		5.1	5.2	3.0	D7852
1000	LM4B AZAC-10	1142.8		5.4	5.5	3.3	D7853

◇Frame Size 80 mm With Electromagnetic Brake

2D & 3D CAD Mass (Rack Mass Included) Stroke Rack Mass Product Name L2 2D CAD L1 kg mm kg High-Speed Type High-Transportable-Mass Type 100 LM4B AZMC-1 243.5 0.7 D7864 3.2 3.3 200 LM4B AZMC-2 341.6 3.5 3.6 1.0 D7865 300 LM4B AZMC-3 443.7 3.8 3.9 1.3 D7866 LM4B AZMC-4 4.1 4.0 1.5 D7867 400 541.9 LM4B AZMC-5 D7868 500 640.1 4.3 4.4 1.8 223.7 600 LM4B AZMC-6 742.2 4.6 4.7 2.1 D7869 LM4B AZMC-7 700 840.4 4.9 5.0 2.4 D7870 942.5 800 LM4B AZMC-8 5.2 5.3 2.7 D7871 900 LM4B AZMC-9 D7872 1040.7 5.5 5.6 3.0 1000 LM4B AZMC-10 1142.8 5.8 5.9 3.3 D7873

• Either 40 (40 mm/s) or 500 (500 mm/s) indicating the maximum rack speed is entered where the box 🗌 is located within the product name.



•LM4 F Type

◇Frame Size 80 mm

2D & 3D CAD

Stroke	Product Name	roduct Name L1 L2		Mass (Rack	Rack Mass	2D CAD	
mm				High-Speed Type	High-Transportable-Mass Type	kg	
100	LM4F AZAC-1	243.5		2.8	2.9	0.7	D7834
200	LM4F AZAC-2	341.6		3.1	3.2	1.0	D7835
300	LM4F AZAC-3	443.7	- 177.7	3.4	3.5	1.3	D7836
400	LM4F□AZAC-4	541.9		3.6	3.7	1.5	D7837
500	LM4F AZAC-5	640.1		3.9	4.0	1.8	D7838
600	LM4F AZAC-6	742.2		4.2	4.3	2.1	D7839
700	LM4F AZAC-7	840.4		4.5	4.6	2.4	D7840
800	LM4F AZAC-8	942.5		4.8	4.9	2.7	D7841
900	LM4F AZAC-9	1040.7		5.1	5.2	3.0	D7842
1000	LM4F AZAC-10	1142.8	1	5.4	5.5	3.3	D7843

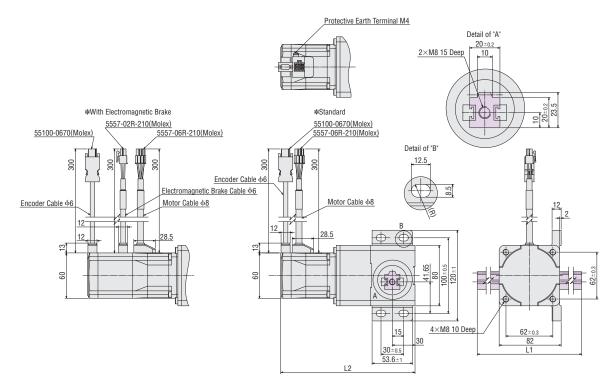
• Either 40 (40 mm/s) or 500 (500 mm/s) indicating the maximum rack speed is entered where the box 🗌 is located within the product name.

◇Frame Size 80 mm With Electromagnetic Brake

2D & 3D CAD

Stroke Product Name		Product Name L1 L2		Mass (Rac	Rack Mass	2D CAD	
mm				High-Speed Type	High-Transportable-Mass Type	kg	
100	LM4F AZMC-1	243.5		3.2	3.3	0.7	D7854
200	LM4F AZMC-2	341.6]	3.5	3.6	1.0	D7855
300	LM4F AZMC-3	443.7	-	3.8	3.9	1.3	D7856
400	LM4F AZMC-4	541.9		4.0	4.1	1.5	D7857
500	LM4F AZMC-5	640.1		4.3	4.4	1.8	D7858
600	LM4F AZMC-6	742.2	223.7	4.6	4.7	2.1	D7859
700	LM4F AZMC-7	840.4] [4.9	5.0	2.4	D7860
800	LM4F AZMC-8	942.5		5.2	5.3	2.7	D7861
900	LM4F AZMC-9	1040.7] [5.5	5.6	3.0	D7862
1000	LM4F AZMC-10	1142.8	1	5.8	5.9	3.3	D7863

• Either 40 (40 mm/s) or 500 (500 mm/s) indicating the maximum rack speed is entered where the box 🗌 is located within the product name.



Peripheral Equipment

Photomicrosensor Sets

A photomicrosensor set, which consists of a photomicrosensor (with flexible cable), sensor mounting bracket, shielding plate and installation screw, is provided to facilitate easy return-to-home operation.

All parts needed for return to home operation are included in the set, so you will spend less time designing, fabricating or procuring parts in connection with sensor installation.

Features

Compact

This is a compact sensor that takes into consideration the installation space. It is easy to detect the rack position.

Two Output Signals are Available

By installing a sensor on both sides of the rack, it is possible to detect two signals at both moving ends or the signals at the moving end and the intermediate stop position, separately.

Product Line

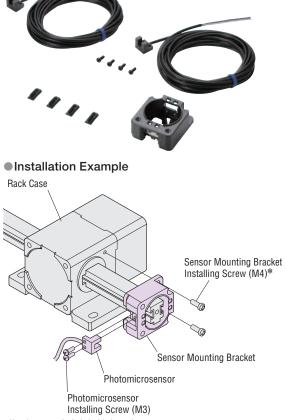
Product Name	Applicable Product	List Price
PARP-PS2B	LM2	\$112.00
PARP-PS4B	LM4	\$112.00

The following items are included with each product.

Photomicrosensors^{*} (2 pieces), Shielding Plates (4 pieces), Sensor Mounting Bracket (1 piece), Photomicrosensor Installation Screws (4 pieces), Operating Manual *With flexible cable (3 m)

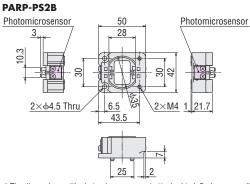
Specifications

Product Name	EE-SX951-R (OMRON)
Power Supply Voltage	5~24 VDC±10%, Ripple (Peak to Peak) 10% max.
Consumption Current	15 mA or less
Control Output	NPN Open-Collector Output, 5~24 VDC, 50 mA or less Residual Voltage: 0.7 VDC or less (At load current of 50 mA) 0.4 VDC or less (At load current of 5 mA)
Indicator LED	Detection Indication (Red)
Logic	Normally Open/Normally Closed (Possible to switch by connection)



*Use the screws included with the rack case.

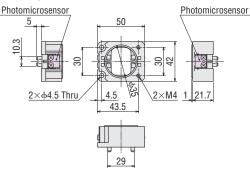
Dimensions (Unit: mm)



• The dimensions with photomicrosensor set attached to L Series are available.

Refer to the Oriental Motor website.

PARB-PS4B



Rack Cover (For Photomicrosensor)

It is a simple cover that protects the rack from impact and particles adhesion.

It also prevents grease from adhering to human body, equipment and so on. Use it together with photomicrosensor set (sold separately).

Product Name	Applicable Product	Applicable Stroke	List Price
2LSC-P02	LM2	100, 200 mm	
2LSC-P04	LMZ	300, 400 mm	See Website
4LSC-P02	LM4	100, 200 mm	See website
4LSC-P04	LIWA	300, 400 mm	



Product Variation with the AZ Series

Controllability is consolidated across all product groups that contain the AZ Series.



Specifications are subject to change without notice. This catalog was published in April, 2019.

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